



Standard Guide for Examination and Evaluation of Pitting Corrosion¹

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1. Scope

1.1 This guide covers the selection of procedures that can be used in the identification and examination of pits and in the evaluation of pitting (See Terminology **G15**) corrosion to determine the extent of its effect.

1.2 *This standard does not purport to address all of the safety concerns, if any, associated with its use. It is the responsibility of the user of this standard to establish appropriate safety and health practices and determine the applicability of regulatory limitations prior to use.*

2. Referenced Documents

2.1 *ASTM Standards:*²

E3 Guide for Preparation of Metallographic Specimens

G1 Practice for Preparing, Cleaning, and Evaluating Corrosion Test Specimens

G15 Terminology Relating to Corrosion and Corrosion Testing (Withdrawn 2010)³

G16 Guide for Applying Statistics to Analysis of Corrosion Data

2.2 *National Association of Corrosion Engineers Standard: NACE RP-01-73 Collection and Identification of Corrosion Products*⁴

3. Significance and Use

3.1 It is important to be able to determine the extent of pitting, either in a service application where it is necessary to predict the remaining life in a metal structure, or in laboratory test programs that are used to select the most pitting-resistant materials for service.

¹ This guide is under the jurisdiction of ASTM Committee **G01** on Corrosion of Metals and is the direct responsibility of Subcommittee **G01.05** on Laboratory Corrosion Tests.

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² For referenced ASTM standards, visit the ASTM website, www.astm.org, or contact ASTM Customer Service at service@astm.org. For *Annual Book of ASTM Standards* volume information, refer to the standard's Document Summary page on the ASTM website.

³ The last approved version of this historical standard is referenced on www.astm.org.

⁴ Insert in *Materials Protection and Performance*, Vol 12, June 1973, p. 65.

4. Identification and Examination of Pits

4.1 *Visual Inspection*—A visual examination of the corroded metal surface is usually beneficial, and this is done under ordinary light, with or without the use of a low-power magnifying glass, to determine the extent of corrosion and the apparent location of pits. It is often advisable to photograph the corroded surface at this point so that it can be compared with the clean surface after the removal of corrosion products.

4.1.1 If the metal specimen has been exposed to an unknown environment, the composition of the corrosion products may be of value in determining the cause of corrosion. Follow recommended procedures in the removal of particulate corrosion products and reserve them for future identification (see NACE RP-01-73).

4.1.2 To expose the pits fully, use recommended cleaning procedures to remove the corrosion products and avoid solutions that attack the base metal excessively (see Practice **G1**). It may be advisable during cleaning to probe the pits with a pointed tool to determine the extent of undercutting or subsurface corrosion (**Fig. 1**). However, scrubbing with a stiff bristle brush will often enlarge the pit openings sufficiently by removal of corrosion products, or undercut metal to make the pits easier to evaluate.

4.1.3 Examine the cleaned metal surface under ordinary light to determine the approximate size and distribution of pits. Follow this procedure by a more detailed examination through a microscope using low magnification (20 \times).

4.1.4 Determine the size, shape, and density of pits.

4.1.4.1 Pits may have various sizes and shapes. A visual examination of the metal surface may show a round, elongated, or irregular opening, but it seldom provides an accurate indication of corrosion beneath the surface. Thus, it is often necessary to cross section the pit to see its actual shape and to determine its true depth. Several variations in the cross-sectioned shape of pits are shown in **Fig. 1**.

4.1.4.2 It is a tedious job to determine pit density by counting pits through a microscope eyepiece, but the task can be made easier by the use of a plastic grid. Place the grid, containing 3 to 6-mm squares, on the metal surface. Count and record the number of pits in each square, and move across the grid in a systematic manner until all the surface has been covered. This approach minimizes eyestrain because the eyes can be taken from the field of view without fear of losing the area of interest.

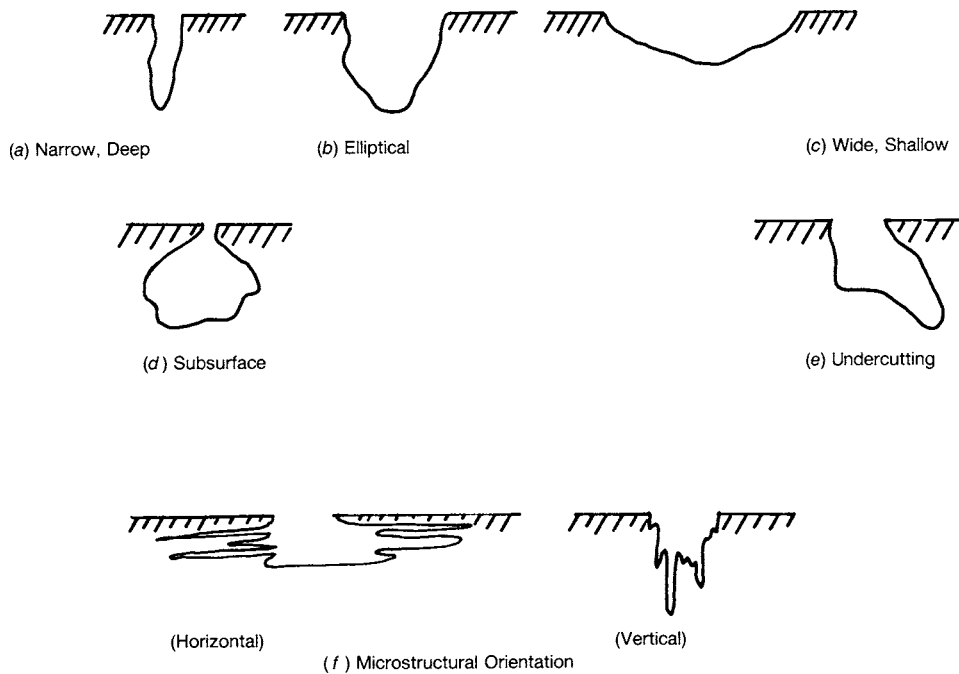


FIG. 1 Variations in the Cross-Sectional Shape of Pits

4.1.5 *Metallographic Examination*—Select and cut out a representative portion of the metal surface containing the pits and prepare a metallographic specimen in accordance with the recommended procedures given in Methods E3. Examine microscopically to determine whether there is a relation between pits and inclusions or microstructure, or whether the cavities are true pits or might have resulted from metal dropout caused by intergranular corrosion, dealloying, and so forth.

4.2 *Nondestructive Inspection*—A number of techniques have been developed to assist in the detection of cracks or cavities in a metal surface without destroying the material (1).⁵ These methods are less effective for locating and defining the shape of pits than some of those previously discussed, but they merit consideration because they are often used in situ, and thus are more applicable to field applications.

4.2.1 *Radiographic*—Radiation, such as X rays, are passed through the object. The intensity of the emergent rays varies with the thickness of the material. Imperfections may be detected if they cause a change in the absorption of X rays. Detectors or films are used to provide an image of interior imperfections. The metal thickness that can be inspected is dependent on the available energy output. Pores or pits must be as large as ½ % of the metal thickness to be detected. This technique has only slight application to pitting detection, but it might be a useful means to compare specimens before and after corrosion to determine whether pitting has occurred and whether it is associated with previous porosity. It may also be useful to determine the extent of subsurface and undercutting pitting (Fig. 1).

⁵ The boldface numbers in parentheses refer to the list of references at the end of this practice.

4.2.2 *Electromagnetic*:

4.2.2.1 Eddy currents can be used to detect defects or irregularities in the structure of electrically conducting materials. When a specimen is exposed to a varying magnetic field, produced by connecting an alternating current to a coil, eddy currents are induced in the specimen, and they in turn produce a magnetic field of their own. Materials with defects will produce a magnetic field that is different from that of a reference material without defects, and an appropriate detection instrument is required to determine these differences.

4.2.2.2 The induction of a magnetic field in ferromagnetic materials is another approach that is used. Discontinuities that are transverse to the direction of the magnetic field cause a leakage field to form above the surface of the part. Ferromagnetic particles are placed on the surface to detect the leakage field and to outline the size and shape of the discontinuities. Rather small imperfections can be detected by this method. However, the method is limited by the required directionality of defects to the magnetic field, by the possible need for demagnetization of the material, and by the limited shape of parts that can be examined.

4.2.3 *Sonics*:

4.2.3.1 In the use of ultrasonics, pulses of sound energy are transmitted through a couplant, such as oil or water, onto the metal surface where waves are generated. The reflected echoes are converted to electrical signals that can be interpreted to show the location of flaws or pits. Both contact and immersion methods are used. The test has good sensitivity and provides instantaneous information about the size and location of flaws. However, reference standards are required for comparison, and training is needed to interpret the results properly.

4.2.3.2 An alternative approach is to use acoustic emissions in detecting flaws in metals. Imperfections, such as pits, generate high-frequency emissions under thermal or mechanical stress. The frequency of emission and the number of occurrences per unit time determine the presence of defects.

4.2.4 *Penetrants*—Defects opening to the surface can be detected by the application of a penetrating liquid that subsequently exudes from the surface after the excess penetrant has been removed. Defects are located by spraying the surface with a developer that reacts with a dye in the penetrant, or the penetrant may contain a fluorescent material that is viewed under black light. The size of the defect is shown by the intensity of the color and the rate of bleed-out. This technique provides only an approximation of the depth and size of pits.

4.2.5 None of these nondestructive test methods provide satisfactory detailed information about pitting. They can be used to locate pits and to provide some information about the size of pits, but they generally are not able to detect small pits, and confusion may arise in attempting to differentiate between pits and other surface blemishes. Most of these methods were developed to detect cracks or flaws in metals, but with more refined development they may become more applicable to pitting measurements.

5. Extent of Pitting

5.1 *Mass Loss*—Metal mass loss is not ordinarily recommended for use as a measure of the extent of pitting unless general corrosion is slight and pitting is fairly severe. If uniform corrosion is significant, the contribution of pitting to total metal loss is small, and pitting damage cannot be determined accurately from mass loss. In any case, mass loss can only provide information about total metal loss due to pitting but nothing about depth of penetration. However, mass loss should not be neglected in every case because it may be of value; for example, mass loss along with a visual comparison of pitted surfaces may be adequate to evaluate the pitting resistance of alloys in laboratory tests.

5.2 *Pit Depth Measurement:*

5.2.1 *Metallographic*—Pit depth can be determined by sectioning vertically through a pre-selected pit, mounting the cross-sectioned pit metallographically, and polishing the surface. The depth of the pit is measured on the flat, polished surface by the use of a microscope with a calibrated eyepiece. The method is very accurate, but it requires good judgment in the selection of the pit and good technique in cutting through the pit. Its limitations are that it is time consuming, the deepest pit may not have been selected, and the pit may not have been sectioned at the deepest point of penetration.

5.2.2 *Machining (2, 3):*

5.2.2.1 This method requires a sample that is fairly regular in shape, and it involves the destruction of the specimen. Measure the thickness of the specimen between two areas that have not been affected by general corrosion. Select a portion of the surface on one side of the specimen that is relatively unaffected; then machine the opposite surface where the pits are located on a precision lathe, grinder, or mill until all signs of corrosion have disappeared. (Some difficulty from galling and smearing may be encountered with soft metals, and pits

may be obliterated.) Measure the thickness of the specimen between the unaffected surface and subtract from the original thickness to give the maximum depth of pitting. Repeat this procedure on the unmachined surface unless the thickness has been reduced by 50% or more during the machining of the first side.

5.2.2.2 This method is equally suitable for determining the number of pits with specific depths. Count the visible pits; then machine away the surface of the metal in measured stages and count the number of visible pits remaining at each stage. Subtract the number of pits at each stage from the count at the previous stage to obtain the number of pits at each depth of cut.

5.2.3 *Micrometer or Depth Gage:*

5.2.3.1 This method is based on the use of a pointed needle attached to a micrometer or calibrated depth gage to penetrate the pit cavity. Zero the instrument on an unaffected area at the lip of the pit. Insert the needle in the pit until it reaches the base where a new measurement is taken. The distance traveled by the needle is the depth of the pit. It is best to use constant-tension instruments to minimize metal penetration at the base of the pit. It can be advantageous to use a stereomicroscope in conjunction with this technique so that the pit can be magnified to ensure that the needle point is at the bottom of the pit. The method is limited to pits that have a sufficiently large opening to accommodate the needle without obstruction; this eliminates those pits where undercutting or directional orientation has occurred.

5.2.3.2 In a variation of this method, attach the probe to a spherometer and connect through a microammeter and battery to the specimen (3, 4). When the probe touches the bottom of the pit, it completes the electrical circuit, and the probe movement is a measurement of pit depth. This method is limited to very regularly shaped pits because contact with the side of the pit would give a false reading.

5.2.4 *Microscopical*—This method is particularly valuable when pits are too narrow or difficult to penetrate with a probe type of instrument. The method is amenable to use as long as light can be focused on the base of the pit, which would not be possible in the case of example (e) in Fig. 1.

5.2.4.1 Use a metallurgical microscope with a magnification range from 50 to 500× and a calibrated fine-focus knob (for example, 1 division = 0.001 mm). If the latter is not available, a dial micrometer can be attached to the microscope in such a way that it will show movement of the stage relative to the microscope body.

5.2.4.2 Locate a single pit on the metal surface and center under the objective lens of the microscope at low magnification (for example, 50×). Increase the objective lens magnification until the pit area covers most of the field under view. Focus the specimen surface at the lip of the pit, using first the coarse and then the fine-focusing knobs of the microscope. Record the initial reading from the fine-focusing knob. Refocus on the bottom of the pit with the fine-focusing knob and record the reading. The difference between the initial and the final readings on the fine-focusing knob is the pit depth.